Chapter 1 Solution of a Large-Scale Traveling-Salesman Problem

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Introduction by Vašek Chvátal and William Cook

The birth of the cutting-plane method

The RAND Corporation in the early 1950s contained "what may have been the most remarkable group of mathematicians working on optimization ever assembled" [6]: Arrow, Bellman, Dantzig, Flood, Ford, Fulkerson, Gale, Johnson, Nash, Orchard-Hays, Robinson, Shapley, Simon, Wagner, and other household names. Groups like this need their challenges. One of them appears to have been the traveling salesman problem (TSP) and particularly its instance of finding a shortest route through Washington, DC, and the 48 states [4, 7].

Dantzig's work on the assignment problem [1] revealed a paradigm for minimizing a linear function $f : \mathbb{R}^n \to \mathbb{R}$ over a finite subset \mathscr{S} of \mathbb{R}^n : first describe the convex hull of \mathscr{S} by a system $Ax \leq b$ of linear constraints and then solve the linear programming problem

minimize f(x) subject to $Ax \le b$

by the simplex method. Attempts by Heller and by Kuhn to apply this paradigm to the TSP indicated that sets of linear constraints describing the convex hull of all tours are far too large to be handled directly. Undeterred, Dantzig, Fulkerson, and Johnson bashed on. The preliminary version of their paper [2] includes a discussion of the convex hull of all tours, nowadays called "the TSP polytope". The version submitted for publication four months later (and eventually published and

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reproduced here) breaks free of the dogma: without letting the TSP polytope obscure their exposition, the authors just go ahead and solve the 49-city instance. (Regarding this change, Fulkerson writes in a September 2, 1954, letter to *Operations Research* editor George Shortly "In an effort to keep the version submitted for publication elementary, we avoid going into these matters in any detail.")

This case study ushered in the cutting-plane method. To solve a problem

minimize
$$f(x)$$
 subject to $x \in \mathscr{S}$ (1.1)

where $f : \mathbb{R}^n \to \mathbb{R}$ is a linear function and \mathscr{S} is a finite subset of \mathbb{R}^n , choose a system $Ax \le b$ of linear inequalities satisfied by all points of \mathscr{S} and use the simplex method to find an optimal solution x^* of the linear programming problem

minimize
$$f(x)$$
 subject to $Ax \le b$, (1.2)

called the *linear programming relaxation* of (1.1). If x^* belongs to \mathscr{S} , then it is an optimal solution of (1.1); else there are linear inequalities satisfied by all points of \mathscr{S} and violated by x^* , called *cutting planes*. Find one or more such inequalities, add them to $Ax \leq b$, and iterate. (The method actually used by Dantzig, Fulkerson, and Johnson—described also in [2, 3]—is a slight variation on this theme: rather than introducing cutting planes only when an optimal solution x^* of (1.2) lies outside \mathscr{S} , they introduce them after each simplex pivot leading to a basic feasible solution x^* of (1.2) that lies outside \mathscr{S} .)

The role played by the convex hull of \mathscr{S} in this new paradigm is only implicit: we have to be able to find a cutting plane whenever one exists, which is the case if and only if x^* lies outside the convex hull of \mathscr{S} . In particular, the number of linear constraints in a description of the convex hull of \mathscr{S} is irrelevant here. Another important difference between the two paradigms is that the cutting-plane method is an engineering rather than mathematical method: unlike the simplex method, it carries no guarantee that the sequence of its iterations will terminate. (But then again, a guarantee of termination after finitely many iterations is a far cry from a guarantee of termination before the end of our solar system.) Our three authors write "... what we shall do is outline a way of approaching the problem that sometimes, at least, enables one to find an optimal path and prove it so."

Until 1954, no one had an inkling of a way to solve large instances of the TSP. The lament about the number of tours through n cities being too large to allow their listing one by one marked the vanguard of scientific progress on this front. Then Dantzig, Fulkerson, and Johnson let the light in and inaugurated a new era. All successful TSP solvers echo their breakthrough. This was the Big Bang.

This Big Bang reverberates far beyond the narrow confines of the TSP. It provides a tempting template for coping with any NP-complete problem of minimizing a linear function over a finite set \mathscr{S} . For each problem of this kind, the challenge lies in finding cutting planes quickly. In the special case of integer linear programming, where \mathscr{S} consists all integer solutions of a prescribed set of linear constraints, this challenge was met with remarkable elegance (and termination after finitely many iterations guaranteed) by Gomory in a series of papers beginning with [5]. Great new ideas may transform the discipline they came from so profoundly that they become hard to discern against the changed background. When terms such as "defense mechanism" and "libido" are in the common vocabulary, it is easy to forget that they came from Sigmund Freud. The cutting-plane method of George Dantzig, Ray Fulkerson, and Selmer Johnson had the same kind of impact on the discipline of mathematical programming.

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SOLUTION OF A LARGE-SCALE TRAVELING-SALESMAN PROBLEM*

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It is shown that a certain tour of 49 cities, one in each of the 48 states and Washington, D. C., has the shortest road distance.

THE TRAVELING-SALESMAN PROBLEM might be described as follows: Find the shortest route (tour) for a salesman starting from a given city, visiting each of a specified group of cities, and then returning to the original point of departure. More generally, given an n by n symmetric matrix $D = (d_{IJ})$, where d_{IJ} represents the 'distance' from I to J, arrange the points in a cyclic order in such a way that the sum of the d_{II} between consecutive points is minimal. Since there are only a finite number of possibilities (at most $\frac{1}{2}(n-1)!$) to consider, the problem is to devise a method of picking out the optimal arrangement which is reasonably efficient for fairly large values of n. Although algorithms have been devised for problems of similar nature, e.g., the optimal assignment problem,^{3,7,8} little is known about the traveling-salesman problem. We do not claim that this note alters the situation very much; what we shall do is outline a way of approaching the problem that sometimes, at least, enables one to find an optimal path and prove it so. In particular, it will be shown that a certain arrangement of 49 cities, one in each of the 48 states and Washington, D. C., is best, the d_{IJ} used representing road distances as taken from an atlas.

* HISTORICAL NOTE: The origin of this problem is somewhat obscure. It appears to have been discussed informally among mathematicians at mathematics meetings for many years. Surprisingly little in the way of results has appeared in the mathematical literature.¹⁰ It may be that the minimal-distance tour problem was stimulated by the so-called Hamiltonian game¹ which is concerned with finding the number of different tours possible over a specified network. The latter problem is cited by some as the origin of group theory and has some connections with the famous Four-Color Conjecture.⁹ Merrill Flood (Columbia University) should be credited with stimulating interest in the traveling-salesman problem in many quarters. As early as 1937, he tried to obtain near optimal solutions in reference to routing of school buses. Both Flood and A. W. Tucker (Princeton University) recall that they heard about the problem first in a seminar talk by Hassler Whitney at Princeton in 1934 (although Whitney, recently queried, does not seem to recall the problem). The relations between the traveling-salesman problem and the transportation problem of linear programming appear to have been first explored by M. Flood, J. Robinson, T. C. Koopmans, M. Beckmann, and later by I. Heller and H. Kuhn.4.5.6

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In order to try the method on a large problem, the following set of 49 cities, one in each state and the District of Columbia, was selected:

1. Manchester, N. H.	18. Carson City, Nev.	34. Birmingham, Ala.
2. Montpelier, Vt.	19. Los Angeles, Calif.	35. Atlanta, Ga.
3. Detroit, Mich.	20. Phoenix, Ariz.	36. Jacksonville, Fla.
4. Cleveland, Ohio	21. Santa Fe, N. M.	37. Columbia, S. C.
5. Charleston, W. Va.	22. Denver, Colo.	38. Raleigh, N. C.
6. Louisville, Ky.	23. Cheyenne, Wyo.	39. Richmond, Va.
7. Indianapolis, Ind.	24. Omaha, Neb.	40. Washington, D. C.
8. Chicago, Ill.	25. Des Moines, Iowa	41. Boston. Mass.
9. Milwaukee, Wis.	26. Kansas City, Mo.	42. Portland Me
10. Minneapolis, Minn.	27. Topeka, Kans	A Baltimore Md
11. Pierre, S. D.	28 Oklahoma City Okla	B Wilmington Del
12. Bismarck, N. D.	20. Dellas Tor	C Philadelphia Dapp
13. Helena, Mont.	25. Danas, Iex.	C. I madelpina, Fenn.
14. Seattle, Wash.	30. Little Rock, Ark.	D. Newark, N. J.
15. Portland, Ore.	31. Memphis, Tenn.	E. New York, N. Y.
16. Boise, Idaho	32. Jackson, Miss.	F. Hartford, Conn.
17. Salt Lake City, Utah	33. New Orleans, La.	G. Providence, R. I.

The reason for picking this particular set was that most of the road distances between them were easy to get from an atlas. The triangular table of distances between these cities (Table I) is part of the original one prepared by Bernice Brown of The Rand Corporation. It gives $d_{IJ} = \frac{1}{17} (d'_{IJ} - 11)$,* $(I,J=1, 2, \cdots, 42)$, where d'_{IJ} is the road distance in miles between I and J. The d_{IJ} have been rounded to the nearest integer. Certainly such a linear transformation does not alter the ordering of the tour lengths, although, of course, rounding could cause a tour that was not optimal in terms of the original mileage to become optimal in terms of the adjusted units used in this paper.

We will show that the tour (see Fig. 16) through the cities $1, 2, \dots, 42$ in this order is minimal for this subset of 42 cities. Moreover, since in driving from city 40 (Washington, D. C.) to city 41 (Boston, Massachusetts) by the shortest road distance one goes through A, B, \dots , G, successively, it follows that the tour through 49 cities $1, 2, \dots, 40$, A, B, \dots , G, 41, 42 in that order is also optimal.

PRELIMINARY NOTIONS

Whenever the road from I to J (in that order) is traveled, the value $x'_{IJ}=1$ is entered into the I,J element of a matrix; otherwise $x'_{IJ}=0$ is entered. A (directed) tour through n cities can now be thought of as a permutation matrix of order n which represents an n-cycle (we assume

* This particular transformation was chosen to make the d_{IJ} of the original table less than 256 which would permit compact storage of the distance table in binary representation; however, no use was made of this.



n>2 throughout). For example, for n=5, the first matrix displayed below

 $\|x_{IJ}^{'}\| = \left| \begin{array}{cccccc} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{array} \right| \,, \qquad \|x_{IJ}^{'}\| = \left| \begin{array}{cccccccc} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{array} \right| \,.$

is a tour since it represents visiting the cities in the 5-cycle $(1\ 2\ 4\ 3\ 5)$, while the other matrix is not a tour since it represents visiting the cities by means of two sub-cycles $(1\ 2)$ and $(3\ 5\ 4)$.

It is clear that all representations for directed tours satisfy the relations

$$\sum_{I} x'_{IJ} = \sum_{J} x'_{IJ} = 1, \qquad x'_{II} = 0, \qquad x'_{IJ} \ge 0.$$

The matrix may be made into a triangular array by reflecting the numbers above the diagonal in the diagonal. The sum of corresponding elements is denoted by $x_{IJ} = x'_{IJ} + x'_{JI}$. Then the matrices above become

$$\|x_{IJ}\| = \left| \begin{array}{cccc} \cdot & & & \\ 1 & \cdot & & \\ 0 & 0 & \cdot & \\ 0 & 1 & 1 & \cdot \\ 1 & 0 & 1 & 0 & \cdot \end{array} \right|, \qquad \|x_{IJ}\| = \left| \begin{array}{cccc} \cdot & & & \\ 2 & \cdot & & \\ 0 & 0 & \cdot & \\ 0 & 0 & 1 & \cdot & \\ 0 & 0 & 1 & 1 & \cdot \end{array} \right|$$

Consequently, the sum along the Kth row plus the sum along the Kth column must now be 2. This may be written

$$\sum_{J < I=K} x_{IJ} + \sum_{I > J=K} x_{IJ} = 2, \qquad (K = 1, \dots, n; \ x_{IJ} \ge 0) \quad (1)$$

This device yields a representation for undirected tours and is the one used throughout this paper. It will be noted that the second array above does not represent a tour but nevertheless satisfies the relation (1).

For undirected tours, the symbol x_{IJ} will be treated identically with x_{JI} so that we may rewrite (1) as

$$\sum_{J=1}^{n} x_{IJ} = 2. \qquad (x_{IJ} \ge 0; \ I = 1, 2, \cdots, n; \ I \neq J; \ x_{IJ} = x_{JI}) \quad (2)$$

The problem is to find the minimum of the linear form

$$D(x) = \sum_{I>J} d_{IJ} x_{IJ},$$
 (3)

where the $x_{IJ}=0$ or 1 and the $x_{IJ}=1$ form a tour, and where the summation in (3) extends over all indices (I,J) such that I>J.

To make a linear programming problem out of this (see ref. 2) one

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needs, as we have observed, a way to describe tours by more linear restraints than that given by (2). This is extremely difficult to do as illustrated by work of I. Heller⁴ and H. Kuhn.⁶ They point out that such relations always exist. However, there seems to be no simple way to characterize them and for moderate size n the number of such restraints appears to be astronomical. In spite of these difficulties, this paper will describe the techniques we have developed which have been successful in solving all the problems we have tried by this approach. A surprising empirical observation is the use of only a trivial number of the many possible restraints to solve any particular problem. To demonstrate the procedure, we shall attempt to use direct elementary proofs even though they were originally motivated in many places by linear programming procedures.

There are possibly four devices we have used which have greatly reduced the effort in obtaining solutions of the problems we have attempted.

First of all, we use undirected tours. This seems to simplify the characterization of the tours when n is small and certainly cuts down the amount of computation, even for large n. Secondly, and this is decisive, we do not try to characterize the tours by the complete set of linear restraints, but rather impose, in addition to (2), just enough linear conditions on the x_{IJ} to assure that the minimum of the linear form (3) is assumed by some tour. For the 49-city problem and also for all the smaller problems we have considered, such a procedure has been relatively easy to carry through by hand computation. This may be due in part to the fact that we use a simple symbolism which permits direct representation of the algebraic relationships and manipulations on a map of the cities. This third device speeds up the entire iterative process, makes it easy to follow, and sometimes suggests new linear restraints that are not likely to be obtained by less visual methods. Finally, once a tour has been obtained which is nearly optimal, a combinatorial approach, using the map and listing possible tours which have not yet been eliminated by the conditions imposed on the problem, may be advantageous. This list can be very much shorter than one would expect, due to the complex interlocking of the restraints. However, except for short discussion in the section below, "An Estimation Procedure," this method will not be described in detail although it has worked out well for all examples we have studied.

An important class of conditions that tours satisfy, which excludes many non-tour cases satisfying (2), are the 'loop conditions.' These are linear inequality restraints that exclude subcycles or loops. Consider a non-tour solution to (2) which has a subtour of $n_1 < n$ cities; we note that the sum of the x_{IJ} for those links (I,J) in the subtour is n_1 . Hence we can

eliminate this type of solution by imposing the condition that the sum of x_{IJ} over all links (I,J) connecting cities in the subset S of n_1 cities be less than n_1 , i.e.,

$$\sum_{s} x_{IJ} \leq n_1 - 1 \tag{4}$$

where the summation extends over all (I,J) with I and J in the n_1 cities S. From (2) we note that two other conditions, each equivalent to (4), are

$$\sum_{\bar{s}} x_{IJ} \leq n - n_1 - 1, \tag{5}$$

where \tilde{S} means the summation extends over all (I,J) such that neither I nor J is in S, and

$$\sum_{ss} x_{IJ} \ge 2, \tag{6}$$

where $S\bar{S}$ means that the summation extends over all (I,J) such that I is in S and J not in S.

There are, however, other more complicated types of restraints which sometimes must be added to (2) in addition to an assortment of loop conditions in order to exclude solutions involving fractional weights x_{IJ} . In the 49-city case we needed two such conditions. However, later when we tried the combinatorial approach, after imposing a few of the loop conditions, we found we could handle the 49-city problem without the use of the special restraints and this would have led to a shorter proof of optimality. In fact, we have yet to find an example which could not be handled by using only loop conditions and combinatorial arguments.

THE METHOD

The technique will be illustrated by a series of simple examples.

Example 1

First consider a five-city map forming a regular pentagon of unit length per side and with length $\frac{1}{2}(\sqrt{5}+1)=1.7$ on a diagonal (Fig. 1). Sup-



pose that the problem is to minimize (3) subject only to (2). Start with a tour which is conjectured to be optimal, obviously (1 2 3 4 5). In this case the values of x_{IJ} , denoted by \bar{x}_{IJ} , are $\bar{x}_{12} = \bar{x}_{23} = \bar{x}_{34} = \bar{x}_{45} = \bar{x}_{51} = 1$ and all other $\bar{x}_{IJ} = 0$. The variables x_{IJ} corresponding to links on the tour are called 'basic variables.' The length of the tour given by the linear form (3) for $x = \bar{x}$ is $D(\bar{x}) = 5$. There are five equations in (2). Multiply each by a parameter π_I to be determined, and then subtract the sum from (3). Thus, we are led to

$$D(x) = \sum_{I>J} d_{IJ} x_{IJ} - \sum_{I=1}^{n} \pi_I \left(\sum_{J=1}^{n} x_{IJ} - 2 \right) \qquad (x_{IJ} \equiv x_{JI}; \ I \neq J)$$
$$= -\sum_{I>J} (\pi_I + \pi_J - d_{IJ}) x_{IJ} + 2 \sum_{1}^{n} \pi_I.$$

Denote the coefficients of x_{IJ} by δ_{IJ} so that

$$D(x) = -\sum_{I>J} \delta_{IJ} x_{IJ} + 2\sum_{1}^{n} \pi_{I}. \qquad (\delta_{IJ} = \pi_{I} + \pi_{J} - d_{IJ}) \quad (7)$$

Now determine the five π_I values so that δ_{IJ} corresponding to basic variables vanish:

$$\delta_{IJ} = 0, \qquad (\text{for } \bar{x}_{IJ} = 1) \quad (8)$$

i.e., if the link (I,J) is on the tour in question. Note that to solve for the π_I we have five linear equations in five unknowns.

If now we set $x_{IJ} = \bar{x}_{IJ}$ in (7), then $\bar{x}_{IJ}\delta_{IJ} = 0$ for all (I,J) and

$$D(\bar{x}) = 2 \sum_{1}^{n} \pi_{I} = 5.$$
(9)

Subtracting (9) from (7) we have finally'

$$D(x) - D(\bar{x}) = -\sum_{I>J} \delta_{IJ} x_{IJ}.$$
 (10)

For the regular pentagon $\pi_I = \frac{1}{2}$ for I = 1, 2, 3, 4, 5 solves (8), and so $\delta_{IJ} = \frac{1}{2}(1 - \sqrt{5}) < 0$ on a diagonal, i.e., $\delta_{IJ} \leq 0$ for every (I,J). Thus, the right side of (10) is always nonnegative or $D(x) \geq D(\bar{x})$ for all x satisfying (2), and in particular all other tours are longer than the tour represented by \bar{x} .

Example 2

Next, take another five-city problem whose map is not a regular pentagon (Fig. 2). We start with the tour $(1\ 2\ 3\ 4\ 5)$ of length $D(\bar{x})=32$ where the basic variables take on the values $\bar{x}_{12}=\bar{x}_{23}=\bar{x}_{34}=\bar{x}_{45}=\bar{x}_{51}=1$ and all other $\bar{x}_{12}=0$. Repeat the steps in the previous problem leading to (10)



FIGURE 2

where, as before, calculate the π_I by setting $\delta_{IJ} = 0$ for δ_{IJ} corresponding to basic variables x_{IJ} . The five equations that the π_I must satisfy are

 $\pi_1 + \pi_2 = 5, \quad \pi_2 + \pi_3 = 5, \quad \pi_3 + \pi_4 = 8, \quad \pi_4 + \pi_5 = 6, \quad \pi_5 + \pi_1 = 8$

By alternately subtracting and adding these equations one obtains.

$$2\pi_1 = d_{12} - d_{23} + d_{34} - d_{45} + d_{51} = 5 - 5 + 8 - 6 + 8 = 10,$$

$$\pi_1 = 5, \quad \pi_2 = 0, \quad \pi_3 = 5, \quad \pi_4 = 3, \quad \pi_5 = 3.$$

or

The factors π_I which multiply equations (2) to form (10) are called 'potentials.'* There is one such potential associated with each city I, and these are readily computed by working directly on the map of the cities (see Fig. 3).



To form other δ_{IJ} , add the π_I and π_J of city I and city J and subtract off the distance d_{IJ} between them. In this case we note that except for $\delta_{31}=5+5-6=+4$, all the other δ_{IJ} are ≤ 0 .

We see from (10) that if x_{31} were to take on a positive value, $x_{31}=\theta$, the other nonbasic variables remaining at zero, this may lead to a better solution. We let θ be the largest value consistent with (2). Thus, the weights x_{IJ} must add up to 2 on links from each city and no weight is negative. However, in setting $x_{31}=\theta$ we adjust only the basic set of variables, leaving all other nonbasic variables at zero value. This is

* The term potential is used by T. C. Koopmans in an analogous connection for the transportation problem.⁵

worked out on the map shown in Fig. 4. Here the maximum value of θ is 1, and this leads to a 3-cycle (1 2 3) and a 2-cycle (4 5) (Fig. 5).

This is not a tour, so we add a loop condition which excludes this solution but which is satisfied by all tours. In this case $x_{45} \leq 1$ or

$$x_{45} + y_6 - 1 = 0, \qquad (y_6 \ge 0) \quad (11)$$

is such a condition. Accordingly, we start over again using the five equations (2) and the sixth equation (11). This time we will need six basic variables and it will be convenient to have x_{13} (the one we set equal to θ previously) included with those associated with the tour. Thus, the



starting solution is as follows: The basic variables have values $\bar{x}_{12} = \bar{x}_{23} = \bar{x}_{34} = \bar{x}_{45} = \bar{x}_{51} = 1$, $\bar{x}_{13} = 0$. All other $\bar{x}_{IJ} = 0$. This solution is shown in Fig. 6. The presence of an upper bound on x_{45} or relation (11) is depicted in Fig. 6 by a block symbol on (4, 5). Now we multiply equation (11) by π_6 , add it to $\sum_{I=1}^{5} \pi_I \left(\sum_{J=1}^{5} x_{IJ} - 2 \right)$, subtract the sum from $\sum d_{IJ} x_{IJ}$ and collect terms in x_{IJ} as before. The result is

$$\sum_{I>J} d_{IJ} x_{IJ} = -\sum_{I>J} \delta_{IJ} x_{IJ} + 2\sum_{I=1}^{5} \pi_{I} + \pi_{6} (1-y_{6})$$
(12)

where $\delta_{IJ} = \pi_I + \pi_J - d_{IJ}$ except $\delta_{45} = \pi_4 + \pi_5 - (d_{45} - \pi_6)$.

Now determine the six values of π_I by setting $\delta_{IJ} = 0$ corresponding to basic variables x_{IJ} :

$$\delta_{12} = \delta_{23} = \delta_{34} = \delta_{45} = \delta_{51} = \delta_{13} = 0, \tag{13}$$

from which it follows that

$$D(x) - D(\bar{x}) = -\sum \delta_{IJ} x_{IJ} - \pi_6 y_6.$$
(14)

To evaluate π_I we note that there are six equations in six unknowns. These are shown on the map below (Fig. 7). The three conditions about the triangular loop (1, 2, 3) permit us to solve for π_1 , π_2 , π_3 . Branching out from the triangle we get next π_4 and π_5 and finally π_6 . Thus, we determine first that $2\pi_1 = d_{12} - d_{23} + d_{31} = 5 - 5 + 6$ so that $\pi_1 = 3$, $\pi_2 = 2$, $\pi_3 = 3$.

Working down, $\pi_4=5$, $\pi_5=5$. Thus, $\pi_4+\pi_5=-\pi_6+6$, so $\pi_6=-4$. These values are shown adjacent to each city in Fig. 7.

With these values of π_I all remaining $\delta_{IJ} = (\pi_I + \pi_J - d_{IJ}) \leq 0$; hence, with $\pi_6 < 0$ we have the right side of (14) always positive, so the tour (1 2 3 4 5) is minimal. This illustrates the use of the simplest of the loop conditions, namely, an upper bound on the variable x_{45} .



Example 3

Here we consider a six-city case (Fig. 8) where the optimal tour is not our initial choice. Let the starting tour be $(1\ 2\ 3\ 4\ 5\ 6)$ of length $D(\bar{x}) =$ 23. If we proceed as before, relation (8) implies that the π_I satisfy the relations shown in Fig. 8. In this case (and this is generally true for



loops with an even number of links) the sum of equations on links (1, 2), (3, 4), (5, 6) is identical with the sum for (2, 3), (4, 5), (6, 1) except for different constant terms, so that the system of equations in π_I is incon-

sistent. This difficulty can be avoided if the following general rule is followed: The set of basic variables must be so selected that when the remaining

 x_{IJ} are fixed, the values of the basic variables are uniquely determined. This means the matrix of coefficients of the basic variables is nonsingular (i.e., their determinant is nonvanishing). Since the π_I satisfy a system of equations whose coefficient matrix is the transpose of this matrix, the π_I will be uniquely determined also. In the six-city case, one may augment system (2) with the additional upper-bound condition

$$x_{45} + y_7 = 1 \qquad (y_7 \ge 0) \quad (15)$$

and select x_{13} as a basic variable in addition to the basic variables x_{IJ} corresponding to (I, J) on the tour. Then, letting π_7 be the weight associated with restriction (15), the π_I satisfy relations in Fig. 9.



The value of $\pi_1 = \frac{5}{2}$ can be determined from the odd loop (123) by alternately adding and subtracting the equations around the loop. The others can then be evaluated immediately. In this case, we have, analogous to (14),

$$D(x) - D(\bar{x}) = -\sum \delta_{IJ} x_{IJ} - \pi_7 y_7, \qquad (16)$$

where $\delta_{IJ} = 0$ if x_{IJ} is a basic variable and $\delta_{IJ} = \pi_I + \pi_J - d_{IJ}$ otherwise. Since $\delta_{46} = 3$, increasing the value of x_{46} to θ (while all other nonbasic variables remain zero), with corresponding adjustments in the basic variables, will yield $D(x) - D(\bar{x}) = -3\theta < 0$. In Fig. 10 it is seen that the largest value of $\theta = 1$ and the resulting solution is Fig. 11, which is not a new tour, but two loops. However, we can exclude this solution by imposing the additional restriction satisfied by all tour solutions

$$x_{12} + x_{23} + x_{31} \le 2$$
, or $x_{12} + x_{23} + x_{31} + y_8 = 2$, $(y_8 \ge 0)$ (17)

since in Fig. 11 the inadmissible solution has $x_{12}+x_{23}+x_{31}=3$. We now start all over again augmenting relations (2) by (15) and (17). Let

the basic variables be the same as before but include x_{46} (i.e., the one we set equal to θ in Fig. 10). Let π_I for 1, 2, \cdots , 8 be the weights assigned to these relations respectively in forming $D(x) - D(\bar{x})$; then the π_I satisfy the relations shown in Fig. 12, where the loop condition (17) is symbolized by the dotted loop in the figure.



The value of $\pi_6=2$ may be evaluated from the odd loop (6 4 3 2 1) by alternately adding and subtracting the equations in π_I shown on this loop. The other π_I can then be immediately determined. This time

$$D(x) - D(\bar{x}) = -\sum \delta_{IJ} x_{IJ} - \pi_7 y_7 - \pi_8 y_8$$
(18)

where $\delta_{IJ} = 0$ for x_{IJ} a basic variable and $\delta_{IJ} = \pi_I + \pi_J - d_{IJ}$ otherwise. Since $\delta_{24} = 1$ while all other $\delta_{IJ} \leq 0$, we set $x_{24} = \theta$; then the adjustments in the values of the basic variables necessary to satisfy (2), (15), (17) are



shown in Fig. 13 and the new solution for $\theta = 1$ is a new tour \bar{x} with length $D(\bar{x}) = D(\bar{x}) - 1 = 22$, Fig. 14. We may now drop $x_{34} = 0$ from the basic set of variables (or alternatively x_{12}) and replace it by x_{24} as a new basic variable. This yields the relations for π_I of Fig. 15. The expression for $D(x) - D(\bar{x})$ is similar to (18). It can now be tested that all $\delta_{IJ} \leq 0$ corresponding to non-basic x_{IJ} , and the coefficients of y_7 and y_8 are $\pi_7 \leq 0$, $\pi_8 \leq 0$, so that the new tour is established as optimal.

AN ESTIMATION PROCEDURE

In any linear programming problem with bounded variables, an estimate is available of how much a basic solution differs from an optimal solution. Let D(x) represent a linear form to be minimized and $D(\bar{x})$ be the value for some basic solution \bar{x} where variables $(x_1, x_2, \dots, x_{n'})$, represented by the symbol x, satisfy a system of equations as well as bounds $0 \le x_J \le r_J$. If the equations are multiplied by weights π_I and substracted from D(x), then (as we have noted earlier)

$$D(x) - D(\bar{x}) = -\sum_{J=1}^{n'} \delta_J x_J \qquad (x_J \ge 0) \quad (19)$$

where π_I are chosen such that $\delta_J = 0$ if the corresponding x_J is a basic variable. We may now split the right side of (19) into positive and negative parts and obtain a lower bound for the difference by dropping the positive part, i.e.,

$$D(x) - D(\bar{x}) = -\sum_{\delta_J > 0} \delta_J x_J - \sum_{\delta_J \le 0} \delta_J x_J, \qquad (x_J \ge 0) \quad (20)$$

$$D(x) - D(\bar{x}) \ge -\sum_{\delta_J > 0} \delta_J x_J \ge -E, \qquad (E \ge 0) \quad (21)$$

where -E is some estimate for the negative part. By setting $x_J = r_J$, we obtain in particular

$$D(x) - D(\bar{x}) \ge -\sum_{\delta_J > 0} \delta_J r_J.$$
(22)

For the traveling-salesman problem the variables x_{IJ} must be either 0 or 1 if x represents a tour. From (20), no link (I, J) can occur in an optimal tour if

$$\delta_{IJ} < -E, \tag{23}$$

hence all corresponding variables x_{IJ} can be dropped from further consideration.

During the early stages of the computation, E may be quite large and very few links can be dropped by this rule; however, in the latter stages often so many links are eliminated that one can list all possible tours that





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use the remaining admissible links. By extending this type of combinatorial argument to the range of values of the 'slack' variables y_{κ} , it is often possible at an earlier stage of the iterative algorithm to rule out so many of the tours that direct examination of the remaining tours for minimum length is a feasible approach.

THE 49-CITY PROBLEM*

The optimal tour \bar{x} is shown in Fig. 16. The proof that it is optimal is given in Fig. 17. To make the correspondence between the latter and its programming problem clear, we will write down in addition to 42 relations in non-negative variables (2), a set of 25 relations which suffice to prove that D(x) is a minimum for \bar{x} . We distinguish the following subsets of the 42 cities:

$S_1 = \{1, 2, 41, 42\}$	$S_5 = \{13, 14, \cdots, 23\}$
$S_2 = \{3, 4, \cdots, 9\}$	$S_6 = \{13, 14, 15, 16, 17\}$
$S_{a} = \{1, 2, \dots, 9, 29, 30, \dots, 42\}$	$S_7 = \{24, 25, 26, 27\}.$
$S_4 = \{11, 12, \dots, 23\}$	

Except for two inequalities which we will discuss in a moment, the programming problem may now be written as the following 65 relations:†

<i>x</i> _{7,6} ≤1,	$x_{4.3} \leq 1$,	$x_{41,1} \leq 1$,	$I=1,\cdots,42),$	$\sum_{J} x_{IJ} = 2 \ (I =$
$x_{20,19} \leq 1$,	$x_{15,14} \leq 1$,	$x_{14.13} \leq 1$,	$x_{12.11} \leq 1,$	$x_{9.8} \leq 1$,
$x_{31,30} \leq 1$,	$x_{29,28} \leq 1,$	$x_{27,26} \leq 1,$	$x_{25.24} \leq 1,$	$x_{23,22} \leq 1$,
$\sum_{s_2,\bar{s}_2} x_{IJ} \ge 2,$	$\sum_{s_1, \bar{s}_1} x_{IJ} \ge 2,$	$x_{37,36} \leq 1$,	$x_{55,34} \leq 1,$	$x_{33,32} \leq 1$,
$\sum_{S_7} x_{IJ} \leq 3.$	$\sum_{s_6} x_{IJ} \leq 4,$	$\sum_{s_5,s_5} x_{IJ} \ge 2,$	$\sum_{S_4,\bar{S}_4} x_{IJ} \ge 2,$	$\sum_{3,\bar{S}_3} x_{IJ} \geq 2,$

The remaining two relations (66 and 67) are perhaps most easily described verbally.

- 66: $x_{14.15}$ minus the sum of all other x_{IJ} on links out of 15, 16, 19, except for $x_{18.15}$, $x_{18.16}$, $x_{17.16}$, $x_{19.18}$, and $x_{20.19}$, is not positive.
- 67: $\sum a_{IJ} x_{IJ} \le 42$, where $a_{23,22} = 2$, $a_{26,25} = 0$, all other $a_{IJ} = 1$ except $a_{IJ} = 0$ if x_{IJ} is a non-basic variable and either (a) I is in S_3 , J not in S_3 , or (b) I or J is 10, 21, 25, 26, 27, or 28.[‡]

These two inequalities are satisfied by all tours. For example, if a tour were to violate the first one, it must have successively $x_{15,14}=1$,

* As indicated earlier, it was possible to treat this as a 42-city problem.

 $\ddagger \Sigma_{S,S} x_{IJ}$ means the sum of all variables where only one of the subscripts I or J is in S. $\Sigma_S x_{IJ}$ means the sum of all variables such that I and J are in S—see relations (4), (5), (6).

‡We are indebted to I. Glicksberg of Rand for pointing out relations of this kind to us.

 $x_{18,15}=1$, $x_{18,15}=1$, but also $x_{19,18}=1$, a contradiction. The argument that each tour satisfies the second inequality is similar. If a tour x exists with $\sum a_{IJ}x_{IJ} > 42$, then clearly $x_{23,22}=1$, and also $x_{10,9}=x_{29,28}=1$, since by (a) these are the only links connecting S_3 and \tilde{S}_3 having non-zero a_{IJ} . (See Fig. 17 to distinguish between basic and non-basic variables.) Moreover, since $a_{2e,25}=0$, it follows from (b) that $x_{25,10}=x_{25,24}=x_{27,26}=x_{28,23}=1$. Again, (b) and the fact that $x_{28,21}=0$ imply $x_{21,20}=x_{22,21}=1$. Now look at city 27. There are three possibilities: $x_{27,24}=1$, $x_{27,22}=1$, or $x_{28,27}=1$. But each of these contradicts the assumption that x is a tour.

These relations were imposed to cut out fractional solutions which satisfy all the conditions (2) and (4). A picture of such a fractional solution, which gives a smaller value for the minimizing form than does any tour, is shown in Fig. 18. Notice that it does not satisfy relation 67.



FIG. 18. A fractional solution x satisfying all loop conditions with $\sum d_{IJ} x_{IJ} = 698$.

We assert that if the weights π_I are assigned to these restraints in the order presented above, then the values as given in Fig. 17 satisfy $\delta_{IJ}=0$ for all variables x_{IJ} in the basis. With these values of π_I in the expression for $D(x) - D(\bar{x})$, all $\delta_{IJ} \leq 0$ corresponding to variables x_{IJ} and π_{43} , π_{44} , \cdots , π_{67} corresponding to variables y_{43}, \cdots, y_{67} are appropriately positive or negative (positive if its y occurs with a minus sign in the relation, negative otherwise) with the exception of $\pi_{52} = \frac{1}{2}$ where $x_{25,24} + y_{52} = 1$. This proves, since $E = \frac{1}{2}$ and all the d_{IJ} are integers, that \bar{x} is minimal. The length $D(\bar{x})$ is 699 units, or 12,345 miles except for rounding errors.

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It can be shown by introducing all links for which $\delta_{IJ} \ge -\frac{1}{2}$ that \bar{x} is the unique minimum. There are only 7 such links in addition to those shown in Fig. 17, and consequently all possible tying tours were enumerated without too much trouble. None of them proved to be as good as \bar{x} .

CONCLUDING REMARK

It is clear that we have left unanswered practically any question one might pose of a theoretical nature concerning the traveling-salesman problem; however, we hope that the feasibility of attacking problems involving a moderate number of points has been successfully demonstrated, and that perhaps some of the ideas can be used in problems of similar nature.

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