Polynomials

In order to do what we need to do, it turns out polynomials will be key, so, lets spend a bit of time recalling some *basics*.

Recall that a polynomial (over \mathbb{R} or \mathbb{C}) is just an expression of the form:

$$P(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

where each of the a_i are numbers (in \mathbb{R} or \mathbb{C}).

The **degree** of a polynomial is the largest number *n* such that $a_n \neq 0$. A degree *n* polynomial is **monic** if $a_n = 1$.

The roots of P(x) are the values λ (in \mathbb{C}) for which $P(\lambda) = 0$.

$$P(x) = x^{2} - 5x + 6 = (x - 2)(x - 3)$$

is a degree 2 monic polynomial with roots 2 and 3.

Polynomial Long Division

Given two polynomials N(x) and D(x) with $D(x) \neq 0$ there are polynomials Q(x) and R(x) (the quotient and the remainder) such that

$$N(x) = Q(x)D(x) + R(x)$$

and the degree of R(x) is strictly less than the degree of D(x).

We say that D(x) divides N(x) if N(x) = Q(x)D(x) or equivalently in the above, if R(x) = 0.

Proposition

 $(x - \lambda)$ divides P(x) if and only if $P(\lambda) = 0$

Example:

With $N(x) = x^2 + 3x + 3$ and D(x) = (x + 2) we have:

$$x^{2} + 3x + 3 = (x + 1)(x + 2) + 1$$

so Q(x) = (x + 1) and R(x) = 1.

Polynomial GCD/LCM

The greatest common divisor of two polynomials A(x) and B(x) is the largest degree (monic) polynomial D(x) such that

D(x)|A(x) D(x)|B(x)

The **least common multiple** of two polynomials A(x) and B(x) is the lowest degree (monic) polynomial L(x) such that

A(x)|L(x) = B(x)|L(x)

The following gives an alternative characterization of the gcd/lcm:

Theorem

If P(x) is any polynomial that divides A(x) and B(x) then P(x) divides the gcd of A(x) and B(x).

If P(x) is any polynomial that is divisible by both A(x) and B(x) then P(x) is divisible by the lcm of A(x) and B(x).

Example:

With $A(x) = (x+5)^2(x+2)$ and B(x) = (x+5)(x+3) the gcd is (x+5) and the lcm is $(x+5)^2(x+2)(x+3)$.

Euclidean Algorithm (Special case)

We say that two polynomial have **no common factors** if their gcd is 1.

Lemma

If $P_1(x)$ and $P_2(x)$ are polynomials with no common factors then there exists polynomials $S_1(x)$ and $S_2(x)$ so that

$$S_1(x)P_1(x) + S_2(x)P_2(x) = 1$$

Proof We prooceed by induction on the sum of the degrees of $P_1(x)$ and $P_2(x)$.

In the base case, both are degree 0, but if $P_1(x) = 0 = P_2(x)$, they have common factors (everything), so at least one of them is a non-zero constant. Which covers the base case. For the inductive case, without loss of generality suppose $P_1(x)$ has degree **not smaller than** that of $P_2(x)$.By the division algorithm we can write:

$$P_1(x) = Q(x)P_2(x) + R(x)$$

where R(x) has degree less than $P_1(x)$. We then know that R(x) and $P_2(x)$ also have no common factors, because any common factor would need to be one of $P_1(x)$ aswell. So by induction there exists $S_2(x)$ and $S_3(x)$ so that

 $S_3(x)P_2(x) + S_1(x)R(x) = 1$

but then

 $1 = S_3(x)P_2(x) + S_1(x)R(x) = S_1(x)P_1(x) + (S_3(x) - S_1(x)Q(x))P_2(x)$

which by setting $S_2(x) = S_3(x) - S_1(x)Q(x)$ gives the result.

Evaluating Polynomials at a Linear Transformation/Matrix

If $P(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_1 x + a_0$ is a polynomial, so $a_i \in \mathbb{R}$ (or \mathbb{C}) then for any linear transformation $L: V \to V$ (respectively any square matrix) when we write P(L) we mean:

$$P(L) = a_n L^n + a_{n-1} L^{n-1} + \cdots + a_1 L + a_0 \operatorname{Id}_V$$

where we recall that

$$L^{\ell} = \overbrace{L \circ L \circ \cdots \circ L \circ L}^{\ell} : V \to V$$

Notice that $P(L) : V \to V$ is a linear transformation because it is a linear combination of linear transformations!

$$P(L)(\vec{v}) = a_n L^n(\vec{v}) + a_{n-1} L^{n-1}(\vec{v}) + \dots + a_1 L + a_0 \operatorname{Id}_V(\vec{v})$$

= $a_n L(L(L(\dots(L(\vec{v}))\dots))) + \dots + a_1 L(\vec{v}) + a_0 \vec{v}$

Notice:

$$L^{\ell} \circ L^{r} = L^{\ell+r}$$

and by convention

$$L^0 = \mathrm{Id}_V$$

Examples

We can do all the calculations with the associated matricies if we prefer. Consider

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

If we have $P(x) = x^3 + 2x^2 + x + 3$ then

$$P(A) = A^{3} + 2A^{2} + A + 3Id_{2}$$

$$= \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}^{3} + 2 \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}^{2} + \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} + 3 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 2 & 4 \\ 0 & 2 \end{pmatrix} + \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 3 & 0 \\ 0 & 3 \end{pmatrix}$$

$$= \begin{pmatrix} 7 & 8 \\ 0 & 7 \end{pmatrix}$$

and so

$$P(A)((1,2)) = \begin{pmatrix} 7 & 8 \\ 0 & 7 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = (23,14)$$

In practice we won't ever need to actually evaluate complicated polynomials at linear transformations, they are mostly a theoretical tool for proving things.

We are now going to give a few basic technical results about evaluating polynomials and linear transformations.

Lemma If P(x) and Q(x) are any two polynomials and R(x) = P(x)Q(x) is their product then

$$P(L) \circ Q(L) = R(L)$$

Proof Idea: This follows from the distributive rule for compositions:

$$(a_r L^r + \cdots + a_1 L + a_0 \operatorname{Id}) \circ (b_\ell L^\ell + \cdots + b_1 L + b_0 \operatorname{Id})$$

The way we expand this product is the same as for polynomials.

Lemma

If P(x) and Q(x) are any two polynomials and $L: V \to V$ is any linear transformation then:

$$P(L) \circ Q(L) = Q(L) \circ P(L)$$

Proof Idea: Use the above and that P(x)Q(x) = R(x) = Q(x)P(x).

Corollary

If we factor $P(X) = Q_1(x)Q_2(x)\cdots Q_m(x)$ then

$$P(L) = Q_1(L) \circ \cdots \circ Q_m(L)$$

and the order of factors can be changed.

Proof Idea: This follows from the above by induction A very important case is if we factor $P(X) = \prod (x - \lambda_i)$ then

$$P(L) = (L - \lambda_1 \mathrm{Id}_n) \circ \cdots \circ (L - \lambda_m \mathrm{Id}_n)$$

and the order in which the roots are presented doesn't matter because these commute.

Lemma

Suppose $L: V \to V$ is any linear transformation. For any polynomials $P_1(x)$ and $P_2(x)$ with $P_1(x)|P_2(x)$ we have

 $\operatorname{Ker}(P_1(L)) \subset \operatorname{Ker}(P_2(L)) \qquad \operatorname{Im}(P_2(L)) \subset \operatorname{Im}(P_1(L))$

Proof Sketch If we write $P_2(x) = Q(x)P_1(x)$ then $P_2(L) = Q(L) \circ P_1(L) = P_1(L) \circ Q(L)$ and we note that we always have

 $\operatorname{Ker}(M) \subset \operatorname{Ker}(N \circ M)$ and $\operatorname{Im}(M \circ N) \subset \operatorname{Im}(M)$.

In the first case, because if $\vec{v} \in \text{Ker}(M)$ then $N \circ M(\vec{v}) = N(\vec{0}) = \vec{0}$. In the second case, because if $\vec{v} \in \text{Im}(M \circ N)$ so that $\vec{v} = M \circ N(\vec{w})$ then $\vec{v} = M(N(\vec{w}))$. This now gives us the result. **Lemma** If P(x) and Q(x) are any two polynomials and $L: V \to V$ is any linear transformation then:

 $P(L) \circ Q(L)$

is injective (respectively surjective, respectively bijective) if and only if each of P(L) and Q(L) is injective (respectively surjective, respectively bijective)

Proof sketch:

First note: f and g injective (resp. surjective, bijective) implies $f \circ g$ injective (resp. surjective, bijective). These are useful facts about functions

Next note: $f \circ g$ injective (resp. surjective) implies g injective (resp. f surjective). These are useful facts about functions

Next note that because $P(L) \circ Q(L) = Q(L) \circ P(L)$ we can apply these results in both orders to conclude the if and only if statements. Again an important case is if we factor $P(X) = \prod (x - \lambda_i)$ then P(L) is injective (respectively surjective, respectively bijective) if and only if all of $(L - \lambda_1 Id_n), \ldots, (L - \lambda_m Id_n)$ are.

Lemma

Suppose P(x) is any polynomial, and $L: V \to V$ any linear transformation. If $L(\vec{v}) = \lambda \vec{v}$ then $P(L)(\vec{v}) = P(\lambda)\vec{v}$.

Proof:

First we claim that for all ℓ we have $L^{\ell}(\vec{v}) = \lambda^{\ell} \vec{v}$, we prove this by induction. The base case $\ell = 0$ is, we leave it as an exercise For the inductive case we assume $\ell > 0$ and that $L^{\ell-1}(\vec{v}) = \lambda^{\ell-1} \vec{v}$ then we have:

$$L^{\ell}(\vec{v}) = L^{\ell-1}(L(\vec{v})) = L^{\ell-1}(\lambda\vec{v}) = \lambda L^{\ell-1}(\vec{v}) = \lambda(\lambda^{\ell-1}\vec{v})$$

and so

$$L^{\ell}(\vec{v}) = \lambda^{\ell}\vec{v}$$

by induction.

To complete the proof, now we may calculate that

$$P(L)(\vec{v}) = a_{\ell}L^{\ell}(\vec{v}) + \dots + a_{1}L(\vec{v}) + a_{0}\mathrm{Id}_{\mathrm{V}}(\vec{v})$$
$$= a_{\ell}\lambda^{\ell}\vec{v} + \dots + a_{1}\lambda\vec{v} + a_{0}\vec{v}$$
$$= (a_{\ell}\lambda^{\ell} + \dots + a_{1}\lambda + a_{0})\vec{v}$$
$$= P(\lambda)\vec{v}$$

which is the result.

Polynomial Invariants of Linear Transformations

In order to describe what we can do, in terms of finding a nice basis, in the case of a linear transformation

 $L: V \rightarrow V$,

it is useful to first take stalk of what we **can not** change, things that can't change, are called **invariants**.

For $L: V \to W$, we could not change the rank! In this context, $L: V \to V$, we will look for more invariants (though we still can't change the rank).

The extra invariants we shall use will come primarily from polynomials we associate to L.

Associating Polynomials to a Linear Transformation

The key strategy for giving invariants of linear transformations $L: V \to V$ is to associate to any such transformation a pair of polynomials.

That is, given L we will define polynomials:

- $\operatorname{char}_{L}(x) = x^{n} + a_{n-1}x^{n-1} + \dots + a_{0}$
- $\min_{L}(x) = x^{m} + b_{m-1}x^{m-1} + \dots + b_{0}$

These polynomials will be the key invariants of linear transformations. (An invariant just means a quantity which can be associated to L that doesn't depend on any choices and so somehow gives information about L) That is:

- The coefficients: a_i are invariants (a_0 and $a_n 1$ especially important and well known, though we won't discuss this).
- The coefficients: *b_i* are invariants.
- The roots of the polynomials are invariants.
- The multiplicities of the roots are invariants.

The key usefulness of these invariants is that because we **can not** change them, they ultimately tell us the limits of what we **can** do.

Suppose $L: V \to V$ is any linear transformation on a finite dimensional vector space V. Pick any basis $\vec{e_1}, \ldots, \vec{e_n}$ for V and let A be the matrix associated to L in this basis. Lemma

The polynomial

$$\det(x \mathrm{Id}_n - A)$$

does not depend on the choice of basis for V. This is A4Q4a

Define the characteristic polynomial of L to be

$$\operatorname{char}_{L}(x) = \det(x \operatorname{Id}_{n} - A)$$

If the polynomial depended on the basis, then it wouldn't be an invariant, but as it does not, it is.

Suppose $L: V \to V$ is any linear transformation on an *n*-dimensional vector space V. Lemma

There exists a non-zero polynomials P(x) such that $P(L) = 0_{V,V}$.

Proof The vector space of linear transformations has dimension n^2 (because *n* by *n* matricies do) but $\text{Id}_n, L, L^2, \ldots, L^{n^2}$ is a list of $n^2 + 1$ vectors, hence is linearly dependent. This dependence gives

$$b_{n^2}L^{n^2} + b_{n^2-1}L^{n^2-1} + \cdots + b_1L + b_0 \mathrm{Id}_n = 0$$

and so

$$P(x) = b_{n^2} x^{n^2} + b_{n^2-1} x^{n^2-1} + \dots + b_1 x + b_0$$

is such a polynomial.

Lemma

There exists a smallest integer ℓ such that there exists a non-zero polynomial P(x) of degree ℓ such that $P(L) = 0_{V,V}$.

Proof-idea This is the well ordering principal.

Lemma

Among polynomials of this smallest degree ℓ there exists a unique non-zero polynomial P(x) such that $P(L) = 0_{V,V}$ and the lead coefficient is 1. **Proof-idea** By dividing by the lead coefficient we can ensure the lead is 1. If P(x) and Q(x) are two such polynomials, then their difference would have degree at most $\ell = 1$ and still have P(L) = 0 have the difference must be the zero polynomial of the

 $\ell - 1$, and still have P(L) - Q(L) = 0 hence the difference must be the zero-polynomial so the solution is unique.

The **minimal polynomial**, $\min_{L}(x)$, of a linear transformation $L: V \to V$ is the lowest degree non-zero monic polynomial P such that

$$P(L): V \to V,$$

is the zero transformation, that is $P(L) = 0_{V,V}$.

Such a thing exists by the previous few lemmas.

The minimal polynomial is primarily a theoretical gadget to prove things. For complicated matricies we almost never compute it directly. We will see how to compute it indirectly from the Jordan canonical form later. Examples Consider

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

The characteristic polynomial is the determinant of

$$\det\left(\begin{pmatrix} x-1 & -1\\ 0 & x-1 \end{pmatrix}\right) = (x-1)^2$$

We notice that

$$A^2 - 2A + \mathrm{Id}_2 = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} - 2 \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

So that with $P(x) = x^2 - 2x + 1$ we have P(A) = 0.

By noticing that with Q(x) = x - a we have

$$Q(A) = egin{pmatrix} 1-a & 1 \ 0 & 1-a \end{pmatrix}
eq egin{pmatrix} 0 & 0 \ 0 & 0 \end{pmatrix}$$

We conclude that

$$\min_A(x) = x^2 - 2x + 1$$

Theorem

Let $L: V \to V$ be any linear transformation of a finite dimensional vector space. If P(x) is any polynomial so that P(L) = 0 then $\min_{L}(x)|P(x)$.

Proof: By the polynomial division algorithm (long division) we can write:

 $P(x) = Q(x)\min_{L}(x) + R(x)$

where the degree of R(x) is strictly less than the degree of $\min_{L}(x)$. By definition $\min_{L}(x)|P(x)$ if and only if R(x) = 0. Now note that:

$$R(L) = P(L) - Q(L)\min_{L}(L) = 0 - Q(L)0 = 0$$

hence R(L) is a polynomial of strictly lower degree than $\min_L(x)$ such that $\min_L(L) = 0$. It follows that R(x) = 0, and hence $\min_L(x)|P(x)$.

This gives us a useful characterization of the minimal polynomial, and we shall use it to prove things about it.

Fact: $\min_{L}(x)$ is the unique monic polynomial that satisfies this property.

(This is a short exercise in polynomial algebra, we will not use it for anything.)

Factors of the Characteristic Polynomial

Lemma

 λ is a root of $\operatorname{char}_{L}(x)$ if and only if $L - \lambda \operatorname{Id}_{V}$ is not injective, that is $\operatorname{Ker}(L - \lambda \operatorname{Id}_{V}) \neq \{\vec{0}\}$. Equivalently, $x - \lambda$ divides $\operatorname{char}_{L}(x)$ if and only if $L - \lambda \operatorname{Id}_{V}$ is not injective. This is on the assignment.

Lemma

 $L - \lambda Id_V$ is not injective if and only if there exists $\vec{0} \neq \vec{v} \in V$ with $L(\vec{v}) = \lambda \vec{v}$ This is on the assignment.

Lemma

 λ is a root of char_L(x) if and only if there exists $\vec{v} \in V$ with $L(\vec{v}) = \lambda \vec{v}$. This is on the assignment.

You have possibly seen the above before in the context of eigenvalues for matricies.

Factors of the Minimal Polynomial

Lemma

Suppose P(x) divides $\min_{L}(x)$ then P(L) is not injective. (This applies in particular when $P(x) = x - \lambda$.) **Proof:**

Write $\min_{L}(x) = P(x)Q(x)$ We note that $Q(L) \neq 0$, because it has strictly lower degree than $\min_{L}(x)$, and thus there is a vector $\vec{v} \in V$ with $\vec{w} = Q(L)(\vec{v}) \neq \vec{0}$. We claim $P(L)(\vec{w}) = \vec{0}$. Indeed we know that

$$P(L)(\vec{w}) = P(L)(Q(L)(\vec{v})) = P(L) \circ Q(L)(\vec{v}) = \min_{L}(L)(\vec{v}) = \vec{0},$$

and so P(L) is not injective.

Lemma

If P(L) is not injective, then P(x) and $\min_{L}(x)$ have a common factor. (In particular if $L - \lambda \operatorname{Id}_{V}$ is not injective then $x - \lambda$ divides $\min_{L}(x)$.) **Proof:**

Assume for the purpose of contradiction that P(x) and $\min_L(x)$ have no common factors then we may write

 $1 = S_1(x)P(x) + S_2(x)\min_{L}(x).$

Now because P(L) is not injective, there exists $\vec{0} \neq \vec{v} \in V$ with $P(L)(\vec{v}) = \vec{0}$. Now we compute:

 $\vec{v} = \operatorname{Id}_{V}(\vec{v})$ $= (S_{1}(L)P(L) + S_{2}(L)\min_{L}(L))(\vec{v}) \quad \text{choice of } S_{1}(x) \text{ and } S_{2}(x)$ $= (S_{1}(L)P(L))(\vec{v}) \quad \min_{L}(L) = 0$ $= S_{1}(L)(P(L)(\vec{v})) \quad \text{definition of composition}$ $= S_{1}(L)(\vec{0}) \quad P(L)(\vec{v}) = \vec{0}$ $= \vec{0}$

But this is a contradiction.

In the linear case the only possible common factor is the whole polynomial.

Factors of the Minimal Polynomial vs the Characteristic Polynomial

Theorem

For any linear transformation $L: V \to V$ the roots of $\operatorname{char}_L(x)$ and $\min_L(x)$ are the same. That is, they are precisely the values λ such that $L - \lambda \operatorname{Id}_V$ is not injective.

Proof:

We have just shown that the roots of $\min_L(x)$ are precisely those λ for which $L - \lambda Id_n$ are not injective.

But we have already seen that these are precisely the roots of $char_L(x)$.

What sort of relationship do you think exists between $\min_{L}(x)$ and $\operatorname{char}_{L}(x)$?

Examples

Consider

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \qquad \qquad \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

Both have characteristic polynomial x^2 . The first has minimal polynomial x^2 , the second has minimal polynomial x.

Theorem (Very special case of a later result)

If the minimal and characteristic polynomial of a matrix are both x^2 then there exists a basis so that the matrix for L is

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

If the minimal polynomial of a matrix is x, then the matrix is the zero matrix.

Idea: Let \vec{v} be any vector such that $L(\vec{v}) \neq \vec{0}$.

Then $\vec{e_1} = L(\vec{v}), \vec{e_2} = \vec{v}$ is a basis with respect to which the matrix is $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$

Theorem(we will not prove, and you don't need)

For 2 by 2 and 3 by 3 matricies the characteristic and minimal polynomials determine if two matricies are similar. So A and B are similar if and only if both the characteristic/minimal polynomials are identical.

Examples

Consider

/0	1	0	0/	(0	1	0	0/
0	0	0	0	0	0	0	0
0	0	0	1	0	0	0	0
0/	0	0	0/	0/	0	0	0/

Both have characteristic polynomial x^4 and minimal polynomial x^2 , but they are not similar. Why?

Natural Questions About Characteristic and Minimal Polynomials

• Given some description of a linear transformation $L : \mathbb{R}^n \to \mathbb{R}^n$, find its minimal and characteristic polynomials.

For the characteristic polynomial you must know the definition, for the minimal polynomial we will come back to this.

• Given some description of a linear transformation $L: V \rightarrow V$, find its minimal and characteristic polynomials. Translate this to a question about matricipal

Translate this to a question about matricies!

- What information do the coefficients contain? are there formulas for these? what sorts of properties do they have? These questions are open ended, we will mostly ignore these.
- What information do the roots contains? are there formulas for these? what sorts of properties do they have?

These questions are open ended, we will come back to this.